

Wiimote Hacking

Wiing up your Wiisome Wiimote
with some Wiitastic Wii Scripts.

Wii.

Anatomy of a Wiimote

☒ Communication:

- ☒ Broadcom 2042 Bluetooth controller chip
- ☒ Acts as a Bluetooth HID device

☒ Inputs

- ☒ Buttons
- ☒ Motion Sensor
- ☒ Infrared (IR) Sensor

☒ Outputs

- ☒ Player LEDs
- ☒ Rumble
- ☒ Speaker

☒ Memory

- ☒ Flash Memory
- ☒ Control Registers

☒ Expansion Port

☒ Batteries



Communication

Wiimote Bluetooth HID

- ❏ Bluetooth HID is directly based on the USB HID
- ❏ Queried with Bluetooth SDP, returns:
 - ❏ Name: Nintendo RVL-CNT-01
 - ❏ Vendor ID: 0x057e
 - ❏ Product ID: 0x0306
- ❏ Max Report frequency of 100/sec
- ❏ Does not use any auth/security features of Bluetooth HID standard



Wiimote Peering

- ☒ Press and hold the “1” and “2” buttons simultaneously or press the red “sync” button under the battery cover
- ☒ Query Wiimote via Bluetooth HID driver on the host device













Wiimote HID Interface

- ❏ HID standard allows devices to be self-describing using a HID descriptor block
- ❏ The HID descriptor block includes an enumeration of available Reports
- ❏ Reports are like network ports assigned to a particular service
- ❏ Reports are unidirectional
- ❏ Query using SDP to get descriptor block including reports, direction, and payload size















Wiimote HID Reports

Output:

-  0x11 (1): Player LEDs, Force Feedback
-  0x12 (2): Report type / ID
-  0x13 (1): Enable IR Sensor
-  0x14 (1): Enable Speaker
-  0x15 (1): Controller Status
-  0x16 (21): Write data
-  0x17 (6): Read data
-  0x18 (21): Speaker data
-  0x19 (1): Mute speaker
-  0x1a (1): IR Sensor Enable 2

Input:

-  0x20 (6): Expansion Port
-  0x21 (21): Read data
-  0x22 (4): Write data
-  0x30 (2): Buttons only
-  0x31 (5), 0x33 (17):
 -  Buttons | Motion Sensing Report
-  0x32 (16), 0x34 (21), 0x36 (21), 0x3d (21):
 -  Buttons | Expansion Port | IR
-  0x35 (21), 0x37 (21):
 -  Buttons | Motion Sensing Report | Expansion Port
-  0x38 (21), 0x3e (21), 0x3f (21):
 -  Buttons | Motion Sensing Report | IR



Inputs

Wiimote Buttons

☒ 12 buttons on the Wiimote:

☒ Power button

☒ D-Pad: Up, Down, Left, Right

☒ A and B buttons

☒ -, Home, and + buttons

☒ 1 and 2 buttons

☒ Button press or release generates Input Report 0x30 containing a 2-byte bitmask with current state of all buttons

☒ Button state mask is also included as first two bytes of all other Input Reports



Button Bitmask Values

☒ 0x0001: 2 button

☒ 0x0002: 1 button

☒ 0x0004: B button

☒ 0x0008: A button

☒ 0x0010: - button

☒ 0x0020: Used with
0x3e or 0x3f

☒ 0x0040: Used with
0x3e or 0x3f

☒ 0x0080: Home button

☒ 0x0100: Left button

☒ 0x0200: Right button

☒ 0x0400: Down button

☒ 0x0800: Up button

☒ 0x1000: Plus button

☒ 0x2000: Used with
0x3e or 0x3f

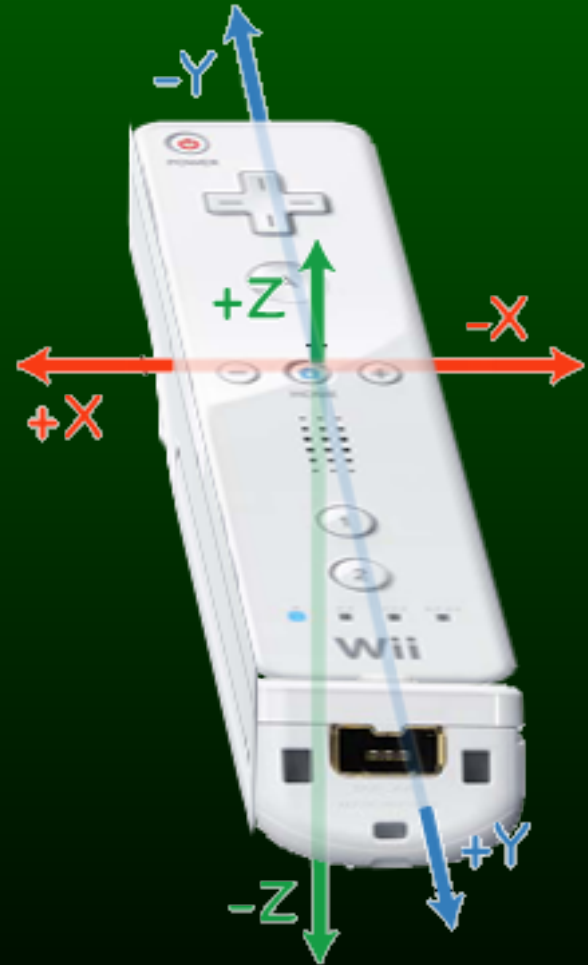
☒ 0x4000: Used with
0x3e or 0x3f

☒ 0x8000: Unknown



Motion Sensor

- ❏ Motion is sensed by an Analog Devices ADXL330 3-axis linear accelerometer located slightly left of the A button
- ❏ Measures acceleration over a range of +/- 3g with 10% sensitivity
- ❏ Forces on each axis are digitized into 8-bit unsigned integers, with the zero scale set to 0x80



Motion Sensor Reports

⊗ Wiimote does not normally report motion sensor data, but can be requested by sending a SET_REPORT request to channel 0x12:

⊗ (a1) 12 00 31

⊗ Wiimote will now send motion sensor reports to channel 0x31 at a frequency determined by parameters to the above SET_REPORT request:

⊗ (a1) 31 40 20 86 8a a5

⊗ Bytes 1 and 2 are the buttons bitmask

⊗ Bytes 3, 4, and 5 are X, Y, and Z axis measurements, respectively

⊗ Other channels that can be used for motion sensor reports include 0x33, 0x35, 0x37, 0x3e and 0x3f

⊗ 0x3e and 0x3f have special properties and extra bytes which may contain IR data

⊗ Reports can be stopped setting the channel to 0x30



Motion Sensor Calibration

- ☒ Zero points and gravity values for the three axes are stored in the Wiimote's flash memory, starting at address 0x16
- ☒ Is repeated at address 0x20:
 - ☒ 0x16: zero point for X axis
 - ☒ 0x17: zero point for Y axis
 - ☒ 0x18: zero point for Z axis
 - ☒ 0x19: unknown
 - ☒ 0x1a: +1G point for X axis
 - ☒ 0x1b: +1G point for Y axis
 - ☒ 0x1c: +1G point for Z axis
 - ☒ 0x1d: unknown
 - ☒ 0x1e - 0x1f: possible checksum



IR Sensor

- ❏ PixArt IR sensor located at the front of the Wiimote housing
- ❏ Possibly a PixArt “System on a Chip” product
- ❏ Locates 2 IR beacons within the IR sensor’s field of view
- ❏ Can detect and transmit up to 4 IR hotspots back to the host
- ❏ Various data sets can be requested, including:
 - ❏ Only position values
 - ❏ Position and size
 - ❏ Position, size, and pixel values



IR Sensor Reports

- ✘ IR Sensor reports 3 bytes of data per dot recognized
- ✘ Bytes 0 and 1 are X and Y positions
- ✘ Byte 2 is the MSBs of X and Y and a size value:
 - ✘ xxxxxxxx yyyyyyyy yyxxSSSS



Outputs

Player LEDs

- ⊠ 4 blue LEDs
- ⊠ Used during play to indicate the player number of the controller
- ⊠ All 4 blink when in Bluetooth discovery mode
- ⊠ Independently controllable via Output Report to channel 0x11 containing LED bitmask:
 - ⊠ (52) 11 10
- ⊠ Most-significant 4 bits control each LED
- ⊠ Updating the LED bitmask rapidly (>1 times per second) causes all 4 LEDs to blink as if in discovery mode, then returns to last known bitmask



Force Feedback (Rumble)

☒ Rumble is achieved via a motor with an unbalanced weight

☒ Can be activated by sending an Output Report to channels 0x11, 0x13, 0x14, 0x15, 0x19 or 0x1a with the LSB set:

☒ (52) 13 01

☒ Can be disabled by clearing the LSB:

☒ (52) 13 00



Speaker

- Small, low-quality internal speaker
- Used primarily for short sound effects during gameplay
- Sound is streamed directly from the host
- Speaker has adjustable parameters
- Controlled via 3 Output Reports together with a section of the register address space
- Report 0x14 is used to enable or disable the speaker by setting or clearing bit 2 of the payload:
 - Enable: (52) 14 04
 - Disable: (52) 14 00
- Report 0x19 is used to mute or un-mute the speaker, used exactly like 0x14



Speaker Initialization

-  To initialize the speaker:
- Enable speaker: Output Report 0x14 of value 0x04
 - Mute speaker: Output Report 0x19 of value 0x04
 - Write 0x01 to register 0x04a20009
 - Write 0x08 to register 0x04a20001
 - Write 7-byte configuration to registers 0x04a20001 - 0x04a20008
 - Write 0x01 to register 04a20008
 - Unmute speaker: Output Report 0x19 value 0x00



Speaker Configuration

7 bytes control all speaker settings:

0x00: unknown

0x01: unknown

0x02: unknown

0x03: Sample rate divisor, based on a start rate of approximately 48000Hz

0x04: Volume control

0x05: unknown

0x06: unknown



Sample Rates and Volume

Known sample rate values:

0x0b: 4000/4364Hz (~4200Hz)

0x0c: 3692/4000Hz (~3920Hz)

0x0d: 3429/3692Hz (~3640Hz)

0x0e: 3200/3429Hz (~3360Hz)

0x0f: 3000/3200Hz (~3080Hz)

Volume:

Any value from 0x00 to 0xff works

0x40 seems to be generally accepted good default



Speaker Data

- Report 0x18 is used to send speaker data
- Up to 20 bytes may be sent at once
- Byte 1 of the payload indicates the length of data, shifted left by 3 bits
- Data must be padded if it is less than the indicated length
- Sound data must be sampled at roughly the proper rate
- Rate can be set during speaker initialization
- Format appears to be 4-bit ADPCM sound



Memory

Flash Memory

- ⊠ Persistent RAM

- ⊠ 5.5K of RAM

- ⊠ Memory Addresses 0x0000 - 0x15ff

- ⊠ Control Registers begin with 0x04 and are 4 byte addresses (0x04a10000)

- ⊠ Addresses wrap after 0xffff



Flash Memory Addresses

- ⊠ 2-byte Addresses ($0x010000 == 0x0000$)
- ⊠ $0x16$ and $0x20$: Calibrated zero offsets for accelerometer
- ⊠ $0x0040 - 0x0fc9$: All zeroes on new Wiimote
- ⊠ $0x0fca - 0x12b9$: Mii data block 1
- ⊠ $0x12ba - 0x15a9$: Mii data block 2
- ⊠ $0x15aa - 0x15ff$: All zeroes on new Wiimote
- ⊠ $0x1600 - 0xffff$: Don't exist, return error on read
- ⊠ $0x010000 - 0xFF0000$ used for control registers



Control Registers

- ⊠ Bit 2 must be set in first byte of address
- ⊠ Bit 1 is the rumble flag and not considered part of the address (0x05a20000 == 0x04a20000)
- ⊠ Only 0x04a20000 - 0x04a30000 are readable



Control Register Addresses

- ☒ 0x04000000 - 0x049fffff: returns error 7 on read
- ☒ 0x04a00000 - 0x04a1ffff: doesn't exist
- ☒ 0x04a20000 - 0x04a30000: speaker
- ☒ 0x04b00000 - 0x04bffffff: returns error 7 on read
 - ☒ 0x04b00000 - 0x04b00008: IR sensitivity settings
 - ☒ 0x04b0001a - 0x04b0001b: IR sensitivity settings
 - ☒ 0x04b00030: IR toggle
 - ☒ 0x04b00033: IR mode
- ☒ 0x04c00000 - 0x04ffffff: returns error 7 on read



Reading Memory

☒ Output Report 0x17 reads memory:

☒ (52) 17 XX XX XX XX YY YY

☒ XX XX XX XX is big-endian formatted address

☒ YY YY is big-endian formatted size in bytes

☒ LSB of first byte is rumble flag and is not part of address, should be set to whatever state the rumble should be

☒ Responses look like:

☒ SE XX XX data...

☒ (a1) 21 80 00 f0 11 f0 80 6c 8c ...

☒ S shifted right 4 bits is size in bytes, minus 1, of current packet

☒ E is error flag:

☒ 8 if reading from bytes that don't exist

☒ 7 if reading from write-only registers

☒ 0 if no error

☒ XX XX is offset of current packet in big-endian format

☒ Rest is data, 16 bytes maximum



Writing Memory

☒ Output Report 0x16 writes memory:

☒ XX XX XX XX SS data...

☒ (52) 16 00 00 00 00 10 57 69 69 ...

☒ XX XX XX XX is the address being written to

☒ SS is the size in bytes

☒ Up to 16 bytes of data, padded

☒ Write acknowledgement is sent on Input Report 0x22

☒ 0x04 as first byte of payload indicates write to control register address

☒ Bit 0 of first byte of payload sets rumble feature

☒ Second byte of payload is ignored unless writing to control register



Expansion Port

Expansion Port

- ✘ Located on the bottom of the Wiimote
- ✘ Used to connect auxiliary controllers which augment the input options of the Wiimote
- ✘ Custom connector with 6 contacts
 - ✘ 2 of the contacts are longer and make contact first when the plug is inserted
- ✘ Communicates with the Wiimote via a 400kHz “fast” I2C, slave address 0x52
- ✘ Available expansions include:
 - ✘ Nunchuk controller
 - ✘ Classic controller



Expansion Port Reports

☒ 0x20: Expansion port status

☒ Sent whenever status changes

☒ Can be requested with Output Report 0x15

☒ bu bu ss uu uu bl

☒ (a1) 20 00 00 02 00 00 c0

☒ bu contains the button state bitmask

☒ ss contains the Expansion Port status bitmask

☒ Bit 0 is unknown

☒ Bit 1 indicates whether or not an attachment is plugged in

☒ Bit 2 indicates whether the speaker is enabled

☒ Bit 3 indicates whether the IR sensor is enabled

☒ Bits 4 - 8 indicate the status of the 4 LEDs

☒ uu contains some unknown bytes

☒ bl contains the battery level



Batteries

Batteries

- ⊠ 2 AA size batteries
- ⊠ Expansion kits containing rechargeable Lithium-Ion batteries and a charging station have hit the market



Battery Reports

0x20: Read battery charge level

- Sent when something is plugged into or unplugged from the expansion port

- Can be requested with Output Report 0x15

- bu bu ss uu uu bl

- (a1) 20 00 00 02 00 00 c0

- bl contains the battery level

- Values as high as 0xc6 have been found

- Suggests that a “fully charged” value may be 0xc8 (200 in decimal)



Expansion Devices

Expansion Devices

- ✘ Use address space 0x04a40000 - 0x04a400ff
- ✘ Must be initialized by writing value 0x00 to address 0x04a40040
- ✘ Byte 3 of address space appears to be ignored (0x04a4ff00 == 0x04a40000)
- ✘ Data is “encrypted” via simple XOR
 - ✘ Decrypt: $\text{value} = (\text{byte} \wedge 0x17) + 0x17$



Expansion Device Addresses

☒ 0x04a40008 - 0x04a4000d:

☒ 6-byte current state of device

☒ 0x04a40020 - 0x04a4002f:

☒ Calibration data

☒ 0x04a40030 - 0x04a4003f:

☒ Repeat of data at 0x04a40020

☒ 0x04a400f0 - 0x04a400ff:

☒ Same on all similar devices, possible device Type ID



Expansion Device Reports

- ⊠ Device must be initialized first
- ⊠ Reports 0x32, 0x34, 0x35, 0x36, 0x37 and 0x3d will contain the 6-byte device status
- ⊠ Data must be “decrypted”
- ⊠ Can also retrieve these bytes by reading 16 bytes starting at address 0x04a40000
 - ⊠ Device status will be at offset 0x08-0x0d
 - ⊠ Different data is returned if you try to read directly from 0x04a40008, so don't try.



Nunchuk Controller State

☒ 6-byte current state of device:

☒ 0x00: X-axis value of analog stick

☒ 0x01: Y-axis value of analog stick

☒ 0x02: Accelerometer X-axis acceleration value

☒ 0x03: Accelerometer Y-axis acceleration value

☒ 0x04: Accelerometer Z-axis acceleration value

☒ 0x05: Button state bitmask:

☒ Bit 0: Z button

☒ Bit 1: C button

☒ Bits 2-3: LSBs from X-axis accelerometer

☒ Bits 4-5: LSBs from Y-axis accelerometer

☒ Bits 6-7: LSBs from Z-axis accelerometer




Classic Controller State









- ☒ 6-byte current state of device:
 - ☒ 0x00: X-axis value of both analog sticks:
 - ☒ Bits 0-5: X-axis of left analog stick
 - ☒ Bits 6-7: Bits 3-4 of X-axis of right analog stick
 - ☒ 0x01: Y-axis value of left analog stick:
 - ☒ Bits 0-5: Y-axis of left analog stick
 - ☒ Bits 6-7: Bits 1-2 of X-axis of right analog stick
 - ☒ 0x02: Y-axis value of right analog stick / Left shoulder button
 - ☒ Bits 0-4: Y-axis of right analog stick
 - ☒ Bits 5-6: Bits 3-4 of left shoulder button
 - ☒ Bit 7: Bit 0 of X-axis of right analog stick
 - ☒ 0x03: Left / Right shoulder buttons
 - ☒ Bits 0-4: Right shoulder button
 - ☒ Bits 5-7: Bits 0-2 of left shoulder button




Classic Controller State

 6-byte current state of device (continued)

 0x04: Button state bitmask 1:

-  Bit 0: unused
-  Bit 1: R button fully pressed
-  Bit 2: + button
-  Bit 3: Home button
-  Bit 4: - button
-  Bit 5: L button fully pressed
-  Bit 6: Down button
-  Bit 7: Right button

 0x05: Button state bitmask 2:

-  Bit 0: Up button
-  Bit 1: Left button
-  Bit 2: ZR button
-  Bit 3: x button
-  Bit 4: a button
-  Bit 5: y button
-  Bit 6: b button
-  Bit 7: ZL button



GlovePIE

Or, why you didn't need to know
any of that lower-level stuff...

What is GlovePIE?

- ☒ Glove Programmable Input Emulator
- ☒ Originally designed for VR gloves
- ☒ Emulates joystick and keyboard input when input is received from other devices
- ☒ Supports the Wiimote as an input device!
- ☒ Can use it to map Wiimote inputs to a game's standard controls
 - ☒ Now you can play WoW with your Wiimote!!!
- ☒ Abstracts away all that lower-layer stuff into a nice object-oriented scripting language
- ☒ Does not work with Microsoft's Bluetooth stack



GlovePIE Scripts

- ✘ GlovePIE creates objects for the hardware it supports
- ✘ Available Wiimote objects of course have methods which implement much of that lower-layer bit and byte necromancy for you
- ✘ Supports variables, flow control, conditionals, etc.
- ✘ Best shown by example...



Example #1: NES Emulator

```
A = Wiimote.Two           //A button "Two" Button
B = Wiimote.One           //B button "One" Button
S = Wiimote.Plus          //Start "Plus" Button
F = Wiimote.Minus         //Select "Minus" Button
Left = Wiimote.Up         //Up is "D pad Left"
Right = Wiimote.Down      //Down is "D pad Right"
Down = Wiimote.Left      //Left is "D pad Down"
Up = Wiimote.Right        //Right is "D pad Up"
D = Wiimote.Home         //Left Shoulder is "Home"
N = Wiimote.B             //Right Shoulder is "B"
```



Example #2: WoW

```
// Setting up the wiimote so that the controls on top of the wiimote works
// as WASD that is commonly used in FPS and other games.
w = Wiimote.Up
s = Wiimote.Down
a = Wiimote.Left
d = Wiimote.Right

// Here I set the nunchuk so it corresponds with my direction keys.
Right = 1 > Wiimote1.Nunchuk.JoyX > 0.5
Left = -1 < Wiimote1.Nunchuk.JoyX < -0.5
down = 1 > Wiimote1.Nunchuk.JoyY > 0.5
up = -1 < Wiimote1.Nunchuk.JoyY < -0.5

// Bind some keys to the mote, you can bind your own.
h = Wiimote.Plus
q = Wiimote.Minus
tab = Wiimote.Home
j = Wiimote.One
k = Wiimote.Two
// Nunchuk
u = Wiimote.Nunchuk.CButton
f = Wiimote.Nunchuk.ZButton
// B for left click and A for right click
mouse.LeftButton = Wiimote.B
mouse.RightButton = Wiimote.A
```



Objects


 Keyboard (also, Key)

 Wiimote



Keyboard Methods


 Most “keys” will work:

 Up, Down, Left, Right, w, a, s, d, Enter, Space, etc.



Wiimote Methods

Buttons:

 Up, Down, Left, Right, A, B, Plus, Minus, Home, One, Two

LEDs:

 Toggles:

 LED1, LED2, LED3, LED4

 Bitmask: LEDs

Rumble:

 Rumble (Boolean, set to 0 or 1)



Demos!

PowerPoint

No demo necessary, I've been using it this entire time...

Knight Rider

Everybody loves blinky LEDs

Wiiibrator 3

This one's for the ladies...

References

 Wii Linux Project Wiimote Page

 <http://www.wiili.org/index.php/Wiimote>

 GlovePIE

 <http://carl.kenner.googlepages.com/glovepie>

